This application claims benefit of the 25 Oct. 2010 filing date of U.S. provisional patent Application No. 61/406,350, and the 1 Feb. 2011 filing date of U.S. provisional patent 5 Application No. 61/438,445.

## FIELD OF THE INVENTION

This invention relates generally to magnetic proximity 10 switches, and particularly to such switches designed for sensing and monitoring the operating position of critical industrial equipment, and opening or closing an electrical circuit in response thereto.

## BACKGROUND OF THE INVENTION

Magnetic proximity switches are used, for example, to sense the position of an industrial valve, for example in nuclear power plants. A magnet or magnetic material called a 20 "target" may be mounted on the valve stem. A magnetic proximity switch is located adjacent to the valve stem so that the target moves within a given distance of the switch when the valve is in a given position, such as fully open or fully closed. The target in this position attracts a magnet in the 25 switch, which closes and/or opens electrical contacts in the switch, resulting in a signal being communicated to a controller. Two proximity switches may be used—one for the open valve position and one for the closed valve position. In this configuration the two switches can confirm each other 30 and can verify that full opening or closing has occurred. An example of such a switch is described in U.S. Pat. No. 7,489, 217.

## BRIEF DESCRIPTION OF THE DRAWINGS

The invention is explained in the following description in view of the drawings that show:

FIG. 1 is a side view of internal parts of a proximity switch according to aspects of the invention with a switch housing in 40 section.

FIG. 2 is a sectional view taken along line 2-2 of FIG. 1.

FIG. 3 is a top view of internal parts of the switch with the shaft support partly cut away to show part of the outer shaft.

FIG. 4 is a top view of the outer shaft.

FIG. 5 is a sectional view of the entire switch taken along a plane of line 5-5 of FIG. 3, with a magnetic target in range, causing leftward movement of the sensor magnet and the movable contact.

target in range, resulting in rightward movement of the sensor magnet and the movable contact.

FIG. 7 is a perspective view of internal parts of the switch.

FIG. 8 is a side sectional view of an embodiment with a connector pin-out adapter.

FIG. 9 is a schematic view of a flexible circuit that connects the switch output leads to input pins on the connector adapter

FIG. 10 is a perspective view of the embodiment of FIG. 8. FIG. 11 is a connector-end view of the embodiment of FIG. 60

FIG. 12 shows an end of the flexible circuit configured for six active pin-out conductors for a double-pole double-throw configuration of the switch.

FIG. 13 shows an end of the flexible circuit configured for 65 three active pin-out conductors for a double-pole doublethrow configuration of the switch.

The present inventors have recognized premature contact wear in prior art magnetic proximity switches, and further have recognized that the wear can result from electrical sparking during contact bounce. The inventors have further recognized that such contact bounce may occur as a result of closure rebound or from operational vibrations and seismic events. The present invention addresses these problems.

FIGS. 1 and 2 show a proximity switch 20 with a housing 22 that has a cable coupler 24 for a signal cable on the right end. Herein, "right" and "left" will be used for convenience to mean toward the cable end 24 of the housing and toward the sensor end 43 of the housing respectively, as shown in FIG. 1. 15 The coupler 24 may have internal threads as known in the art. An inner shaft 26 slides linearly within an outer shaft 28, which slides linearly between the housing 22 and a shaft support 29 that is fixed relative to the housing. A contact block 30 is attached to the right end of the outer shaft 28. It supports one or more bi-directional movable contacts 32 that alternately close against first and second fixed contacts 34, 38. This switching action alternately creates and breaks continuity between pairs of leads 36 held by a lead block 37.

A sensor magnet 42 is attached to the left end of the inner shaft 26 in a retainer 27, and functions as a magnetic target proximity sensor. A return spring 44 urges the inner shaft rightward. An engagement pin 46 is attached to the inner shaft 26 and extends through a slot 45 in the outer shaft 28 and through a slot 47 in the shaft support 29. The engagement pin 46 alternately pushes open one of two locking claws 48, 52. In FIG. 1 the pin 46 is moving leftward, and is pushing open the left claw 52. Each claw 48, 52 pivots to hook or release a respective locking post 56, 58. The locking posts 56, 58 extend from the outer shaft 28 through slots 57, 59 in the shaft 35 support 29. Each claw 48, 52 is urged toward its locked position by a respective spring 49, 53. The claw axles 50, 54 extend from the shaft support 29, thus they remain in a fixed location relative to the housing 22.

FIG. 2 is a sectional view taken along line 2-2 of FIG. 1. A valve stem 60 (not necessarily to scale) is shown proximate the left end 43 of the proximity switch 20. A magnet 62 or magnetic material may be attached to the valve stem to function as a target for the proximity switch. When the valve stem 60 is in a given position, the target is opposite the left end or sensor end 43 of the proximity switch 20, and thus attracts the sensor magnet 42, which moves the inner shaft 26 leftward. This moves the engagement pin 46 leftward, which opens the left claw 52 as shown in FIG. 1.

Before this claw release occurs, the outer shaft 28 is locked FIG. 6 is a sectional view as in FIG. 5, with no magnetic 50 into position relative to the housing 22 so that the left movement of the inner shaft 26 compresses a spring 64 that is retained between two spring blocks 66, 68 that slide within a spring chamber 65 in the inner shaft 26. Movement of the spring blocks 66, 68 is limited by guide pins 67, 69 that extend from the spring blocks through guide slots 70 in the inner shaft 26 and through corresponding guide slots 71 in the outer shaft, as later shown. This spring mechanism 64, 66, 67, 68, 69, 70, 71 causes an accumulation of spring force that urges the outer shaft 28 in the direction of movement of the inner shaft 26, so that when the respective claw (52 for leftward movement) is released by the engagement pin 46, the outer shaft suddenly moves relative to the housing in the direction of the inner shaft, either left or right (leftward in the illustrated case). This causes the movable contact 32 to close suddenly against the left or right stationary contact respectively (the left contact 34 in this case). At that time, the opposite claw (the rightward claw 48 in this case) hooks the opposite locking